

Localization in the Crowd with Topological Constraints

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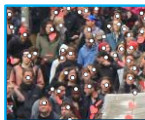


Stony Brook University

Computer Science

INTRODUCTION

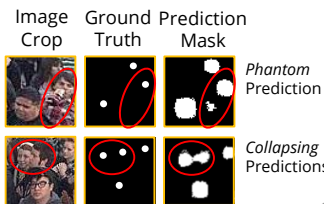
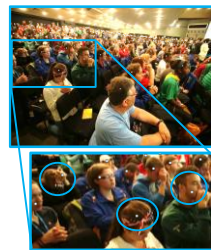
Crowd Localization:



Input Image + Groundtruth Dots

- Predicts the location of each person in a crowded scene.
- Explainable crowd counting.
- Extends to any dense population (animal, biological cells, etc.)
- Important for spatial analysis.

Challenges:



Contributions

- > Formulate crowd localization as a structured prediction problem.
- > Overcome crowd localization challenges by introducing topological constraints in the training phase.
- > Propose persistence loss to enforce topological constraints.
- > Achieve high quality localization that is useful for crowd counting and spatial analysis.
- > Paper and code: <https://github.com/TopoXLab/TopoCount>

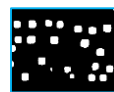
METHOD: TopoCount



Input Image



Ground Truth



Prediction Mask

Topological Constraint for Crowd Localization

Within any local patch, the number of connected components in the prediction equals to the number of ground truth dots.

Persistence Loss \mathcal{L}_{Pers}



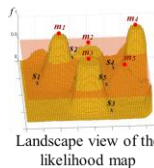
Input Patch



Ground Truth



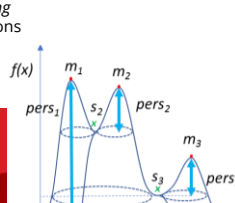
Likelihood Map



Landscape view of the likelihood map



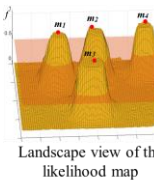
Prediction Mask



After training



Likelihood Map



Landscape view of the likelihood map



Prediction Mask

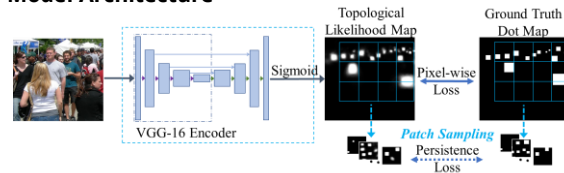
Saliency/Persistence of a mode $Pers(m_i) = f(m_i) - f(s_i)$

Given a patch δ with c groundtruth dots, M_c top c salient modes, $\overline{M_c}$ other modes.

\mathcal{L}_{Pers} Reinforces the total saliency of the top c modes of f and suppresses the saliency of the rest:

$$\mathcal{L}_{Pers}(f, \delta) = - \sum_{m \in M_c} Pers(m) + \sum_{m \in \overline{M_c}} Pers(m)$$

Model Architecture



EVALUATION

Dot Matching Accuracy

Method	F1 / Pre. / Rec. (%)
TinyFaces (Hu et al. 2017)	56.7 / 52.9 / 61.1
VGG+GPR (Gao et al. 2019)	52.5 / 55.8 / 49.6
RAZ Loc (Liu et al. 2019)	59.8 / 66.6 / 54.3
TopoCount	69.1 / 69.5 / 68.7

Input Image



Estimated Topological Map

F-score = 0.85, Count Error = +56

